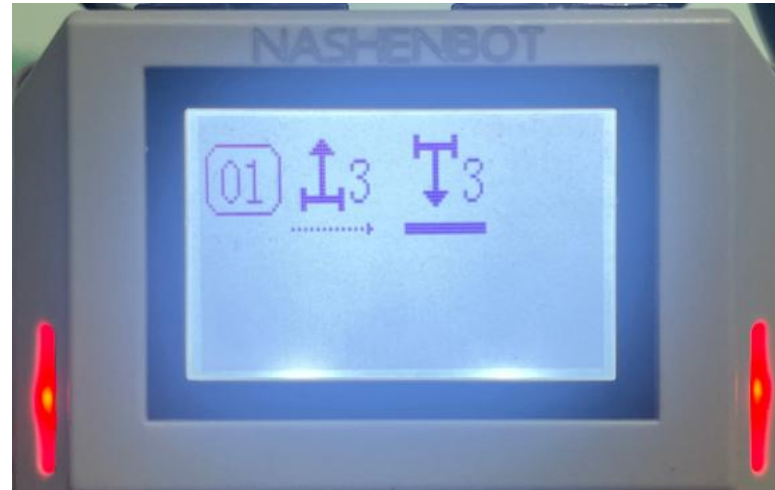


GAR 2026 Future City

VersionB-26 solution by MPBOT S1

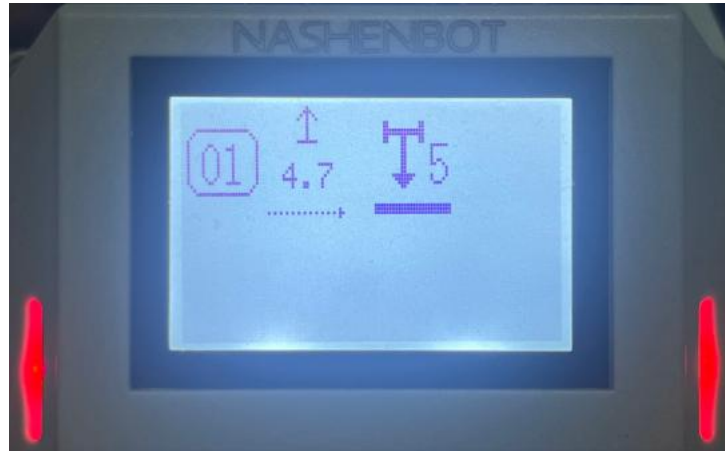
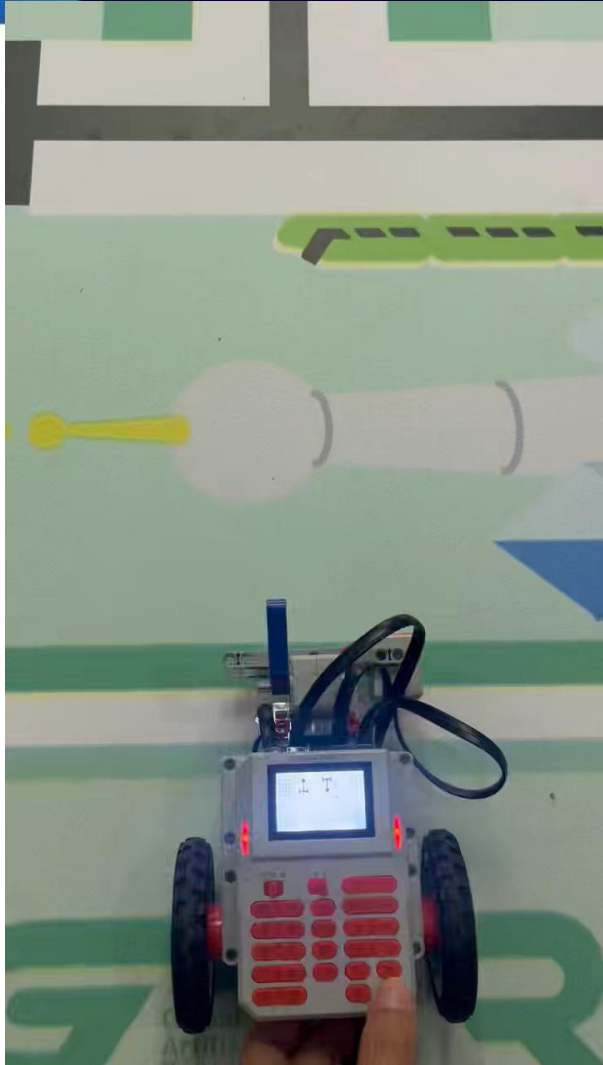


Protect green plants



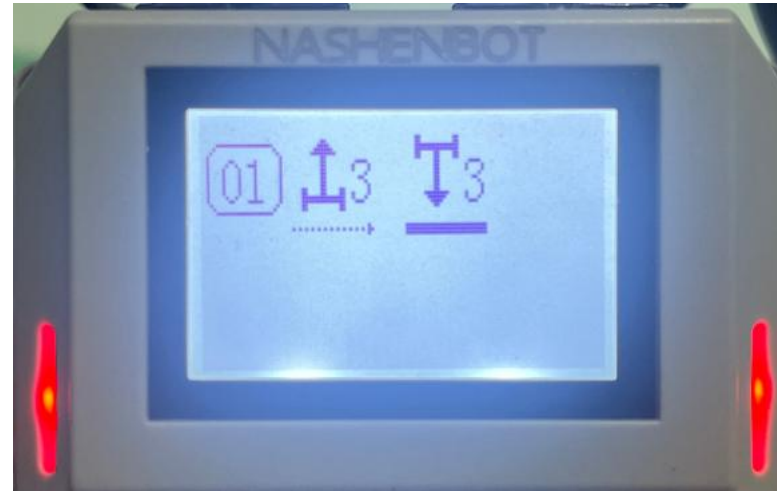
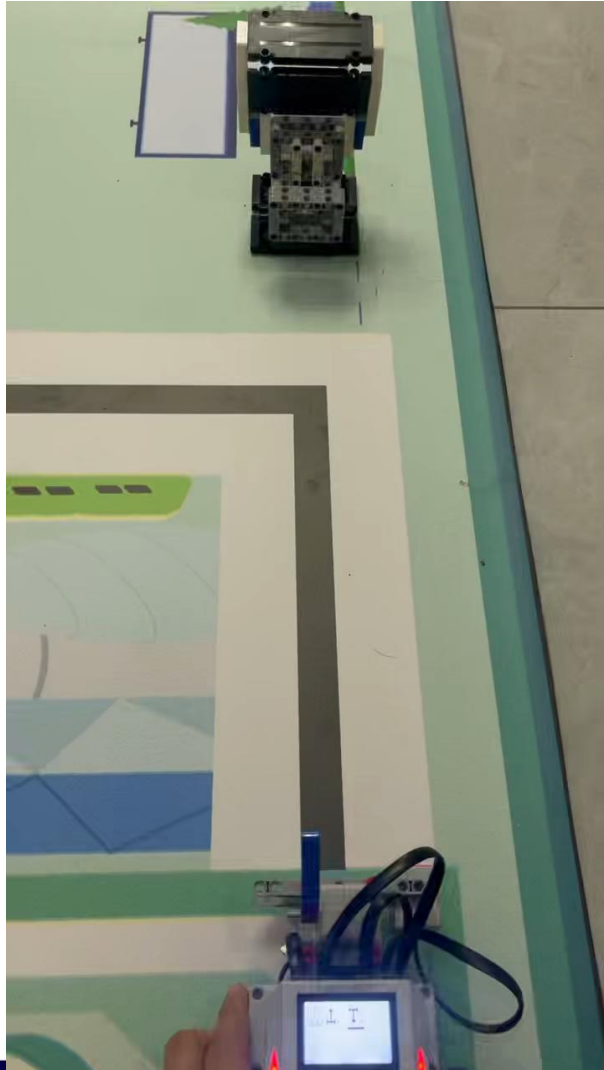
Power switch: high speed

Energy supply



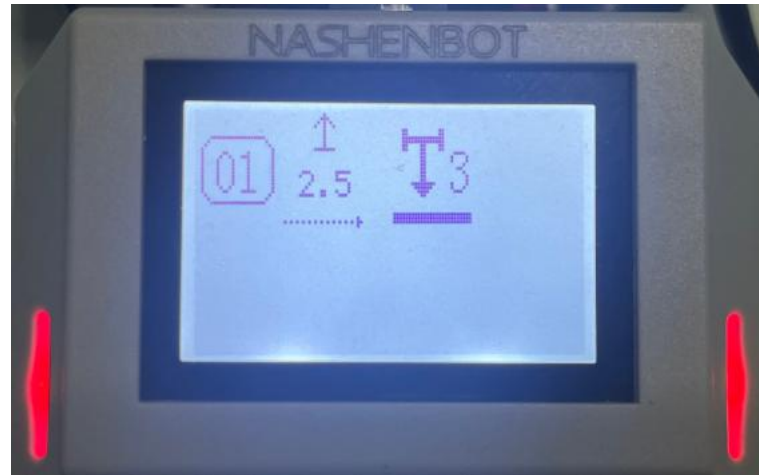
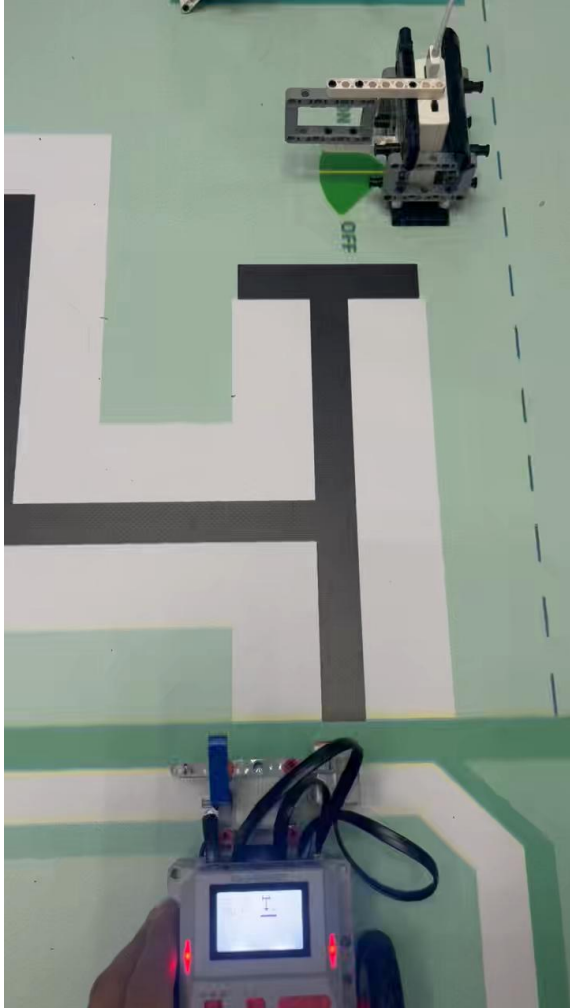
Power switch: high speed

Switch billboards



Power switch: high speed

Automatic factory



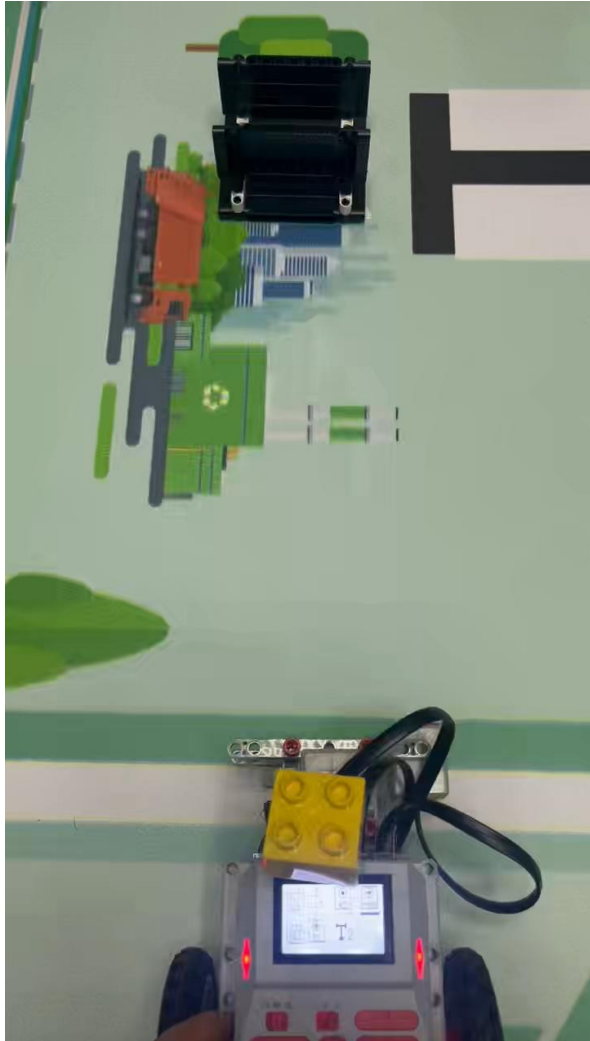
Power switch: high speed

Control the robot's forward movement time carefully:

Too long → it will damage/break the model.

Too short → it won't be able to toggle the model's switch.

End garbage



Power switch: high speed

Road inspection & Glory flashes

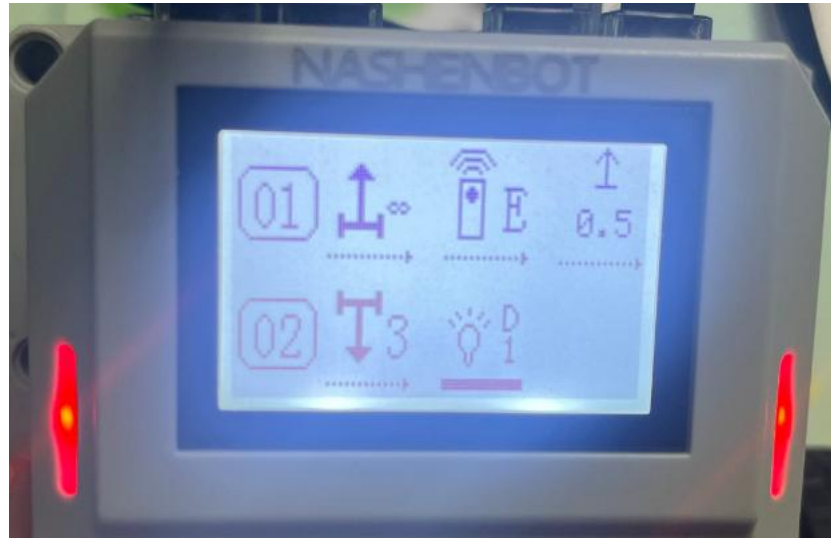


Non-Infrared sensor Version

Power switch: high speed

Non-Infrared sensor Version: Simply control the movement time to reach the appropriate position.

Road inspection & Glory flashes



Infrared sensor Version

Power switch: high speed

Different infrared obstacle avoidance sensors have varying detection distances. If the detection distance is long, control Motor A to advance a little further. If the detection distance is short and the robot collides with the model, move the infrared obstacle avoidance sensor mounting position backward (further to the rear).